



# SAGRO10 GNSS Guidance System User Manual

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## Table of Content

## **Chapter 1 Introduction**

1.1	01	verview3
1.2	Sy	stem Composition3
Cha	pter	2 Equipment Assembly
2.1	Ar	itenna Installation5
2.2	Та	blet Installation
2.3	Ca	ble Installation6
Cha	pter	3 System Operations
3.1	Ma	ain Interface
3.2	Se	tup Interface
3.3	Sta	art Job Interface
	3.3.1	Top Status Bar
	3.3.2	Left Toolbar
	3.3.3	Operation buttons
3.4	Jo	b List Interface
3.5	W	ork Flow14
	3.5.1	System Setting
	3.5.2	Create A New Task
Cha	pter	4 Appendix
4.1	Da	ntasheet
	4.1.1	T10 GNSS Tablet
	4.1.2	SA100 GNSS Antenna

## 1.1 Overview

The SAgro10 guidance system consists of a tablet integrated with a high-precision GNSS module, a geodetic antenna and the guidance software that can intelligently manage the working field and simplify the operation of users, including the recording of the completed work area, the planning and navigation of the work route, etc., which greatly reduces manual mistakes and improves work efficiency. It can be widely used for sowing, cultivating, trenching, ridging, spraying pesticide, transplanting, land consolidation, harvesting and other work scenarios.

The SAgro10 guidance system is compatible with most agricultural tractors, and all components can be easily installed within 20 minutes. Moreover, the SAgro10 guidance system can be easily upgraded to an auto-steering system. On the basis of keeping all components unchanged, only need to add a SEM1(SingularXYZ Electric Motor) to the SAgro10 guidance system to easily upgrade it to auto-steering system, freeing users' hands and improving work efficiency.

This manual will introduce how to install and how to use the SAgro10 guidance system.

### **1.2 System Composition**

The SAgro10 guidance system mainly includes one T10 Control Tablet and one SA100 GNSS antenna. The detailed packing list is shown in the table below.

No.	Name	Quantity	Figure
1	T10 Tablet	1	
2	SA100 GNSS Antenna	1	a de la constante de la consta
3	Main Transmission Cable	1	
4	Power Cable	1	

Table 1: Packing list of SAgro10 automated steering system

5	GNSS Antenna Cable	1	Ó
6	RAM Bracket	1	
7	Antenna Bracket	1	
8	Accessories	1	
9	4G Antenna	1	

## Chapter 2 Equipment Assembly

This chapter introduces how to install the SAgro10 system.

#### 2.1 Antenna Installation

When installing the SA100 GNSS antenna, it needs to be installed on the centerline on the top of the tractor.



Figure 2.1 Antenna installation-1

The SA100 GNSS antenna should be connected to the GNSS connector (ANT1) on the back of the T10 tablet via a GNSS antenna cable.



Figure 2.2 Antenna installation-2

## 2.2 Tablet Installation

The T10 tablet should be installed in the driver cab of the tractor on the RAM bracket, which is shown as

#### below.



Figure 2.3 Tablet installation-1



Figure 2.4 Tablet installation-2

## 2.3 Cable Installation

The cable connection is shown in the figures below.



Figure 2.5 Cable installation

- 1. The 4G antenna is connected to the 4G connector on the right side of the T10 tablet back.
- 2. The main transmission cable should be connected to PORT 2 on the back of the T10 tablet.



Figure 2.6 Main transmission cable

- 3. The power cable are connected to the main transmission cable, which has Power label on it.
- 4. The power supply cable should connect to the vehicle battery. (Support both 12V and 24V)

## Chapter 3 System Operations

### 3.1 Main Interface

For the SAgro10 guidance software, there are 3 main interfaces including Start Job, Job List and Setup interface.



Figure 3.1 Main interface

## 3.2 Setup Interface

Before starting the guidance task, please setup the related settings first.

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_							
<u>.</u>	Width					+ Add	farm 🔻
5	Setup LastPass	Steer A	ngle: 13	0.0  •	Steer Distar	nce: 1.0	times width
	Select Serial Port	Se	erial Port:	/dev/ttyS0	Baud Ra	ate: 11	5200
ô	Guide Direction				Direction (	) Oppos	ite Direction
*	View type					Text	○ Image
CORS	CORS						>
æ	Check for update						>
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Figure 3.2 Setup interface

+ Add farm	•
	+ Add farm

Click to add or delete farm tools, including the width and joint width setting.

Back	Settings	* 🖓 💆 🗷 8:02
<u>*</u>	Width Add farm tools	+ Add farm 🔻
	Select Ser	Rate: 115200
	Guide Dire Junction(m):	Opposite Direction     Text
CORS	CORS Concel OK	
3	Check for update	>
	<b>む, く O ロ む»</b>	

Figure 3.3 Add farm tools

2. LastPass Steer Angle: 130.0	Steer Distance:	1.0 times width
--------------------------------	-----------------	-----------------

Parameters of "LastPass" redirection, please keep the default parameters.

3 Guida Direction	ô	Guide Direction	Opposite Direction
3. Guide Direction			

Set whether the guide arrow in **Start Job** interface is points to the heading direction or deviates from the direction.

4 View Type	View type	Text	○ Image
I. VIEW Type			

Set the menu display of **Start Job** interface.

Sate State On	n width:4.0m km/h 8.3	Sate State SBAS	0m Width: 5.0m km/h 8.1
Hide Track	Straight	26	(日本) (日本) (日本) (日本) (日本) (日本) (日本) (日本)
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Figure 3.4 View type (Left: Text; Right: Image)



Set the CORS account, including the IP, port, mountpoint, username and passwords.

Mount list

Figure 3.5 CORS setting interface

## 3.3 Start Job Interface

After configuration setup, users can conduct the guidance task in Start Job interface, which is shown in the figure below.



Figure 3.6 Job start interface

#### 3.3.1 Top Status Bar



- Delete track: Click to delete current track.
- . Reset track: Click to reset the AB line at the current tractor location.
- 4. Home: Click to return main interface.
- 5. Click to zoom in and zoom out the operating interface.

#### 3.3.3 **Operation buttons**

On the right side of Start Job interface, you can select work modes and start job.



Straight line work mode, including AB line and ABC line.

1) AB line: Click Set A and Set B in turn to set point A and B, the straight guidance lines will be generated based on AB two points.



Figure 3.7 AB line

2) ABC line: After setting AB line, click Set C when the tractor reaches the boundary. The boundary will be generated based on point C.





2. AB Curve work mode.

Click Set A and Set B in turn to set point A and B, the guidance curve will be generated according to the trajectory between points AB.



Figure 3.9 AB curve



- Last Pass: Generate the AB line for the next trip according to the trajectory of the previous trip.
- 4. Set Sign Point: Guide the user toward the guidance point according to the set guidance point.



Figure 3.10et Sign Point

## 3.4 Job List Interface

Back Job List						
Job Name	Guide Type	Area	Length of			
190514203025	Curve Guide	0.115	0.009	Start	Clear	Delete
190514203014	Straight Guide	0.123	0.01	Start	Clear	Delete
190514202731	Straight Guide	0.235	0.011	Start	Clear	Delete
190514202720	Straight Guide	0.144	0.012	Start	Clear	Delete
190514202633	Straight Guide	0.705	0.04	Start	Clear	Delete
190514202622	Curve Guide	0.116	0.011	Start	Clear	Delete
190514203216	Straight Guide	3.836	0.015	Start	Clear	Delete
190514203341	Straight Guide	16.912	0.039	Start	Clear	Delete
190514202855	Curve Guide	3 238	0.047	Start	Clear	Delete
0015147117855	<b>⊲</b> >	$\triangleleft$	0 [	⊐ <b>⊲</b> »		Pastarte

All guidance job information of is saved in the job list interface

Figure 3.11 Job list interface

#### 3.5 Work Flow

After system installation, you can start your work tasks according to the following steps.

#### 3.5.1 System Setting

Set the farm tools and the width in **Setup** >> **Width**, refer to **chapter 3.2 – 1**.

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Back		Setti	ngs		
<u>.</u>	Width			+ A	dd farm 🔻
5	Setup LastPass	Steer Angle:	130.0	Steer Distance:	1.0 times width
	Select Serial Port	Serial F	Port: /dev/ttyS0	Baud Rate:	115200
ô	Guide Direction		⊖ Positi	ive Direction 🔍 Op	posite Direction
*	View type			•	Text O Image
CORS	CORS				>
Э	Check for update				>
	<b>り</b>	< ○ ○		<b>占</b> 》	

Figure 3.12 Setup interface

#### Note:

The default GNSS navigation mode is single-point smooth positioning. If you have additional requirements for higher positioning accuracy, the **RTK** positioning mode is also available in SAgro10 system.

*Go to* **Setup** *interface, connect to the* **CORS** *by entering and applying your CORS account, the detailed instructions please refer to* **chapter 3.2 – 5***.* 

#### 3.5.2 Create A New Task

After configuration, go to **Start Job** interface and select your working mode on the right side, which includes Straight line, Curve, Last Path and Set sign point 4 modes. The detailed instructions about each work mode please refer to **chapter 3.3.3**.

The prompt box for creating a new job will pop up after selecting the work mode, as shown in Figure 3.13. You can start your navigation task after creating tasks.

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Figure 3.13 Create a new job

## 4.1 Datasheet

#### 4.1.1 T10 GNSS Tablet

#### Table 2: T10 Datasheet

System					
Operation System	Android 6.0				
СРИ	Quad-Core 1.5GHZ				
RAM	2GB				
ROM	16GB				
Flash	T flash, up to 64GB				
Display					
LCD	10.1" HD				
Brightness	750Nits, sunlight readable				
Resolution	1024×600 pixels				
Touch Panel	Capacitive screen				
GNSS	Specifications				
GPS	L1, L2				
GLONASS	L1, L2				
BDS	B1, B2				
Galileo	E1, E5b				
QZSS	L1, L5				
SBAS	WAAS, EGNOS, MSAS, GAGAN				
RTK Accuracy	H: 10mm+1ppm, V: 15mm+1ppm				
Heading Accuracy	0.1°				
Timing Accuracy	20ns				
Velocity Accuracy	0.03m/s				
Data Format	RTCM 2.3/3.0/3.2, NMEA0183				
Data Update Rate	Maximum 20Hz				
Electrical & Physical					

Input voltage	9-36 VDC				
Power consumption	≤4.5W				
Size	281×181×42mm				
Weight	1.5 Kg				
Environmental					
Waterproof & dustproof					
Water proof a austproof	IP65				
Shock	IP65 Designed to survive a 2m drop onto concrete				
Shock Operating temperature	Designed to survive a 2m drop onto concrete -20 °C to + 70 °C (-4 °F to 158 °F)				
Shock Operating temperature Storage temperature	Designed to survive a 2m drop onto concrete -20 °C to + 70 °C (-4 °F to 158 °F) -40 °C to + 85 °C (-40 °F to 185 °F)				

### 4.1.2 SA100 GNSS Antenna

Table 3: SA100 GNSS Antenna

Signal Tracking					
GPS	L1, L2, L5				
GLONASS	L1, L2				
BeiDou	B1, B2, B3				
Galileo	E1, E5a/E5b, AltBoc				
SBAS	+				
L-Band	+				
L	NA				
Impedance	50 Ohm				
Polarization	RHCP				
Axial Ratio	≤3dB				
Azimuth Coverage	360°				
Gain at Zenith	5.5dBi				
Phase Center Accuracy	±2mm				
LNA Gain	40dB				
Noise Figure	≤2dB				
VSWR Output	≤2.0				
Operation Voltage	3 - 18VDC				

Operation Current	≤45mA					
Ripple	±1dB					
Group Delay	<5ns					
Physical						
Dimension	Ф152x62.2mm					
Connector	TNC Female					
Weight	374g					
Mounting Configuration	5/8"x 11 Threaded					
Environmental						
Operating Temperature	-40°C to +85°C					
Environmentally Sealed Type	IP67					
Humidity	95% No-condensing					